

# Social Learning and Distributed Hypothesis Testing



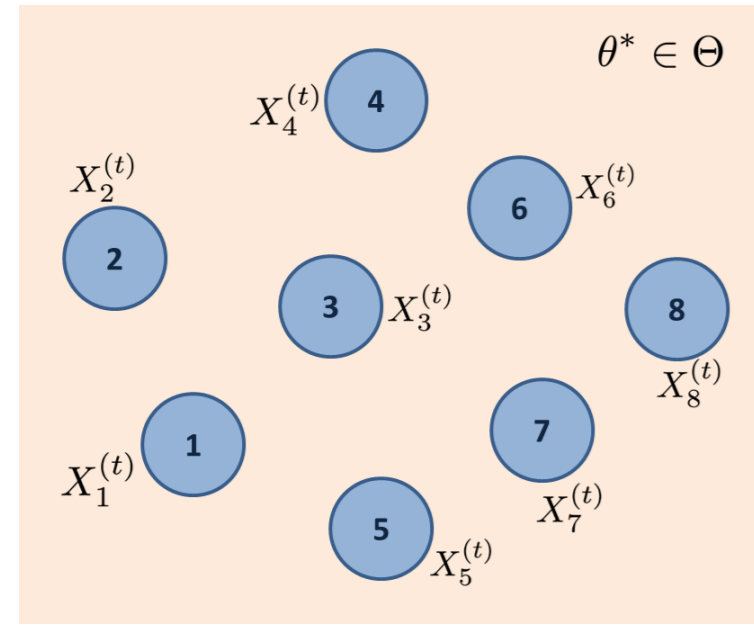
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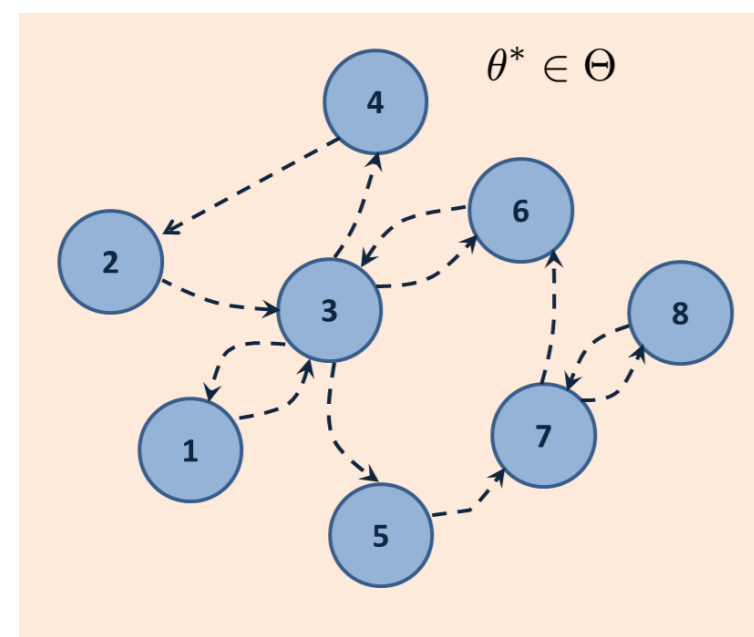
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## Model

- A set of "n" nodes and a finite set of "M" hypotheses  $\Theta = \{\theta_1, \theta_2, \dots, \theta_M\}$ .
- Nodes make observations  $X_i^{(t)}$  at every time instant.
- Observations are statistically governed by fixed true hypothesis  $\theta^*$ .



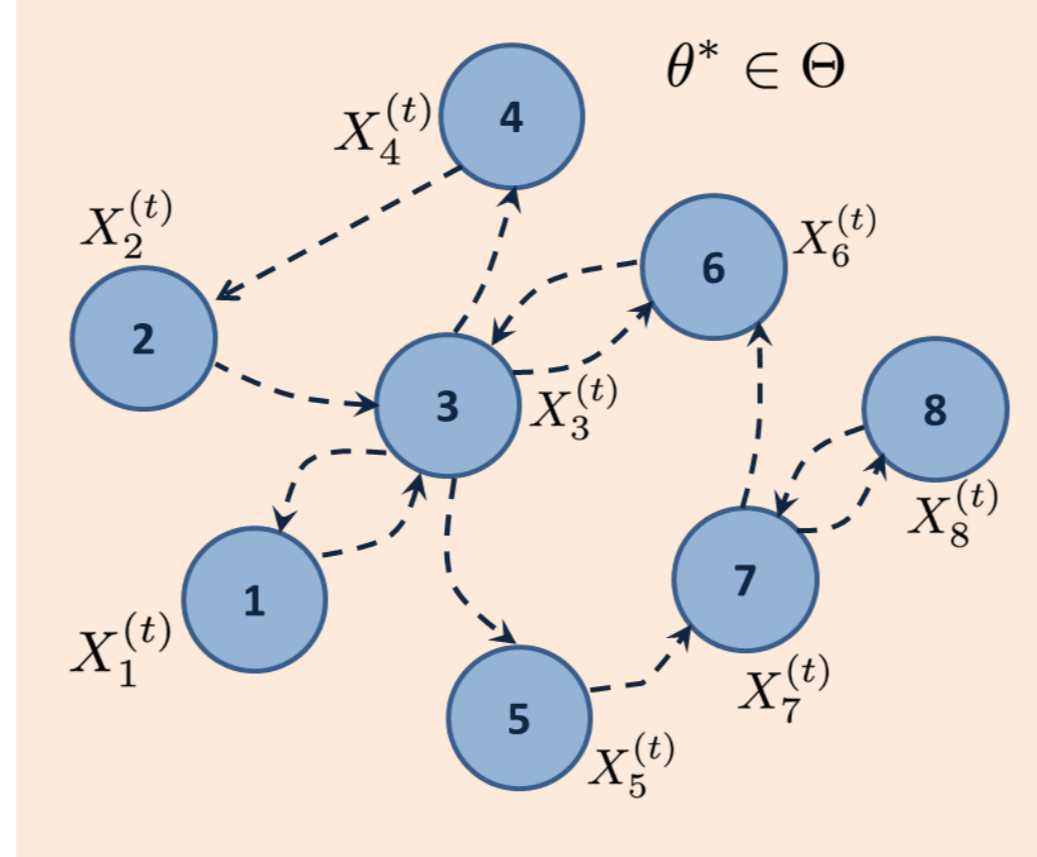
- Each node knows the conditional likelihood functions under each hypothesis. The set is given as  $\{f_i(\cdot; \theta) : \theta \in \Theta\}$
- Nodes are connected in a strongly connected network.



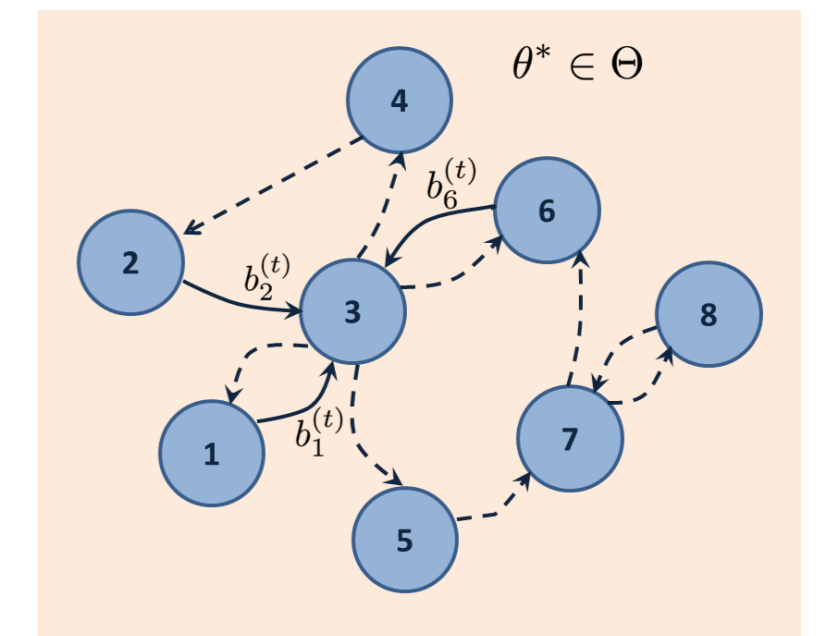
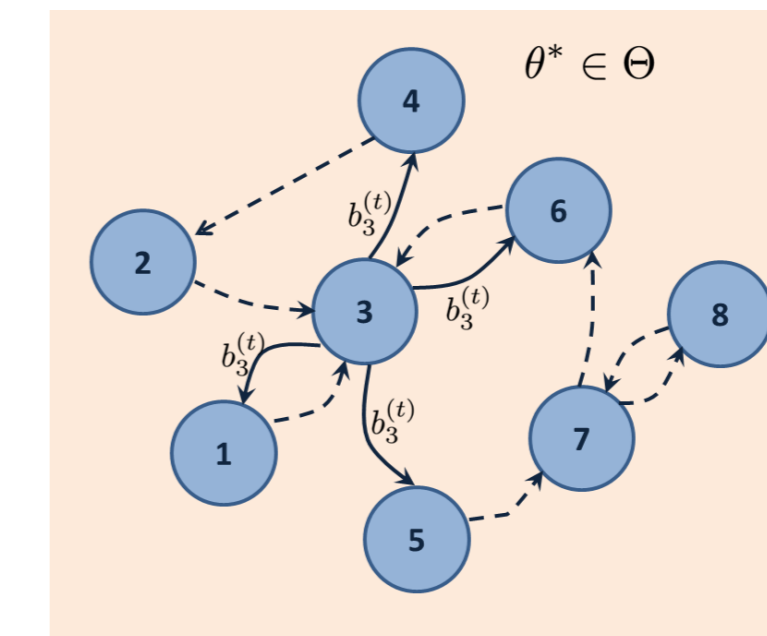
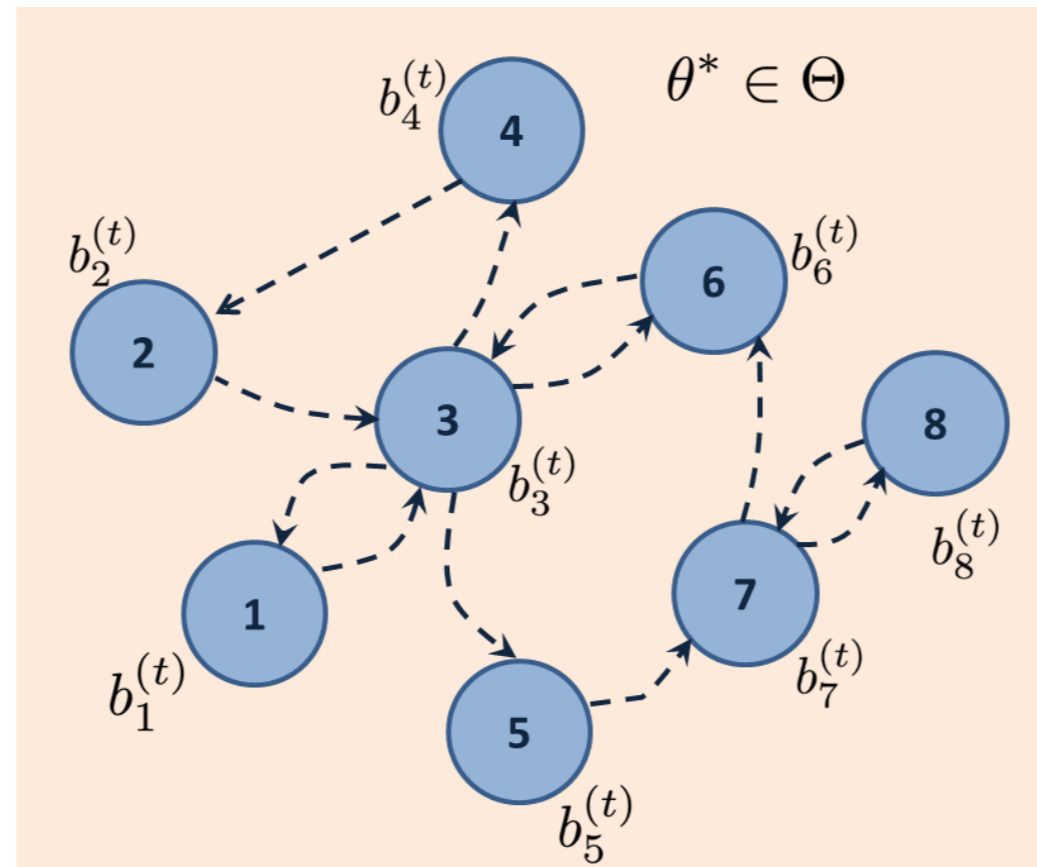
Goal is the parametric inference of the fixed unknown global hypothesis  $\theta^*$  with  $n$  nodes.

## Learning Rule

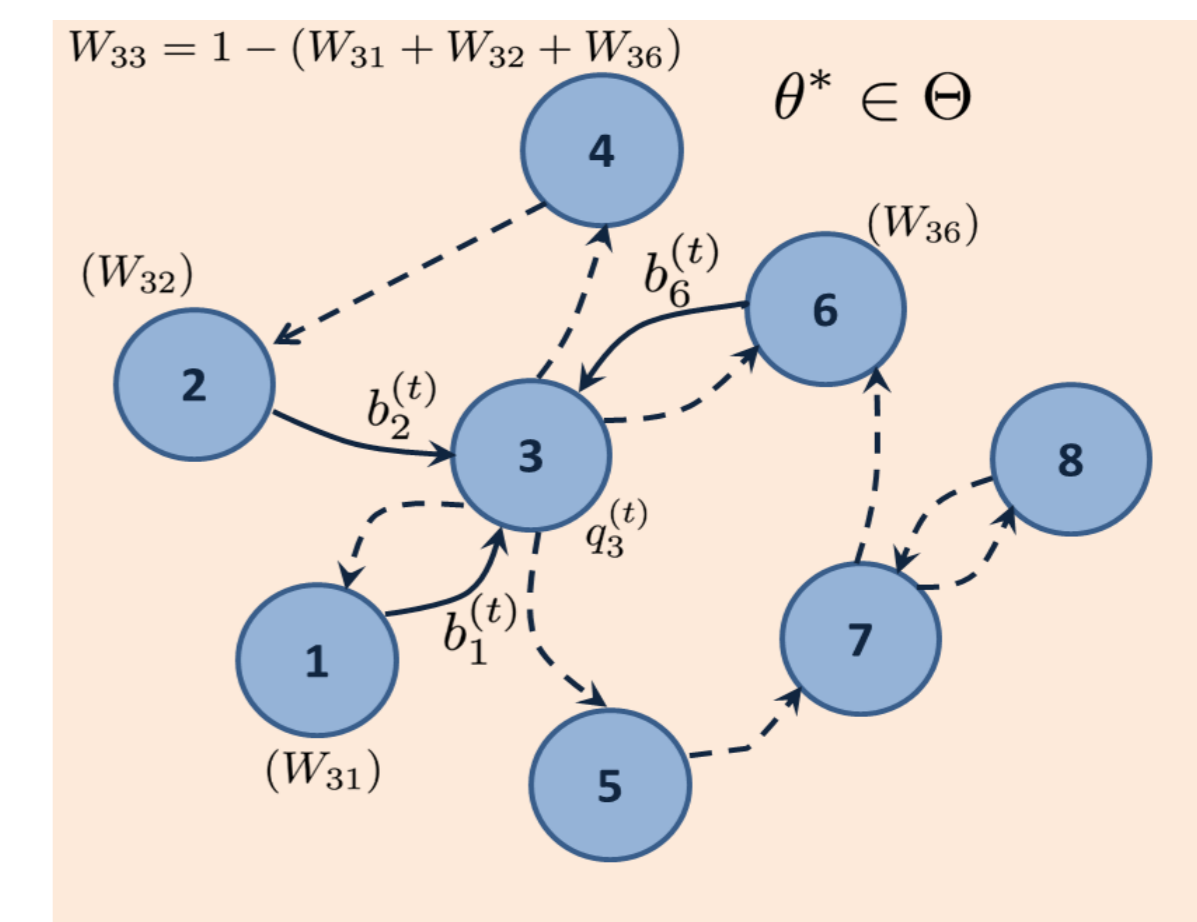
- Every node begins with a strictly positive prior on each hypothesis.
- **Making observation:** At every time instant ( $t > 0$ ), nodes make observations,  $X_i^{(t)}$ .
- **Exchanging beliefs through network:** Each node then sends its belief vector to the neighboring nodes. Similarly receives the belief vectors of its neighbours.



- **Bayesian update of belief:** Every node using its observations performs a Bayesian update of its belief vector,  $b_i^{(t)}$ , which is probability vector on the set of hypotheses.



- **Updating estimate as average of log-beliefs:** Using the belief vectors from the neighbors, each node updates its local estimate vector,  $q_i^{(t)}$ , which is also a probability vector on the set of hypotheses. Estimate vector is computed as the average of log-beliefs using weights.



## Rate of Convergence

- Weight  $W_{ij} > 0$  if and only if there is an edge from node  $i$  to node  $j$  and  $W_{ii} = 1 - \sum_{j=1}^n W_{ij}$ .
- Markov chain defined by weight matrix  $W$  is irreducible.
- The Markov chain defined by  $W$  has a unique stationary distribution,  $\mathbf{v} = \{v_1, v_2, \dots, v_n\}$ , which is the left eigenvector of  $W$  associated with eigenvalue 1.
- For any  $\theta$  not equal to true hypothesis, we define the network divergence as

$$K(\theta^*, \theta) = \sum_{j=1}^n v_j D(f_j(\cdot; \theta^*) || f_j(\cdot; \theta))$$

### Theorem:

For every node in the network, the estimate of wrong hypothesis  $\theta \neq \theta^*$  computed using the proposed learning rule converges to zero exponentially fast with probability one. Furthermore, the rate of rejecting hypothesis  $\theta$  in favor of  $\theta^*$  is given by the network divergence between  $\theta$  and  $\theta^*$ .

$$\lim_{t \rightarrow \infty} \frac{1}{t} \log q_i^{(t)}(\theta) = K(\theta^*, \theta)$$

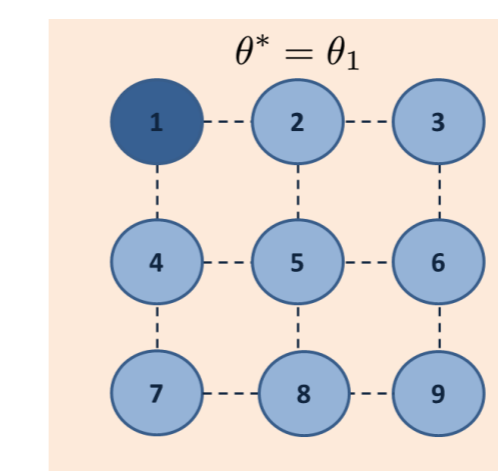
## Factors influencing convergence

Rate of rejecting  $\theta$  in favor of  $\theta^*$  is influenced by eigenvector centrality and the KL-divergence between conditional likelihood functions of  $\theta$  and  $\theta^*$ .

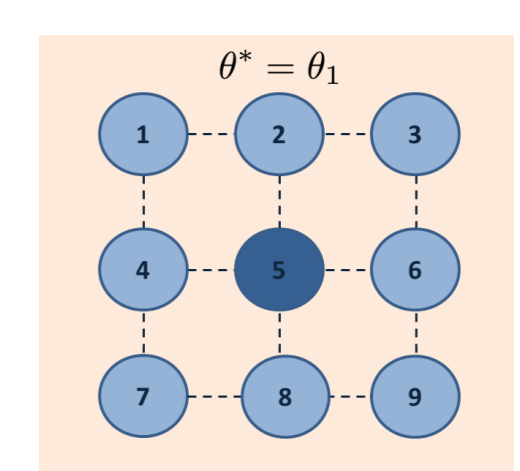
- Set  $\Theta = \{\theta_1, \theta_2, \theta_3, \theta_4\}$  and  $\theta^* = \theta_1$
- If node  $i$  is connected to node  $j$

$$W_{ij} = \frac{1}{\text{degree of node } i}$$

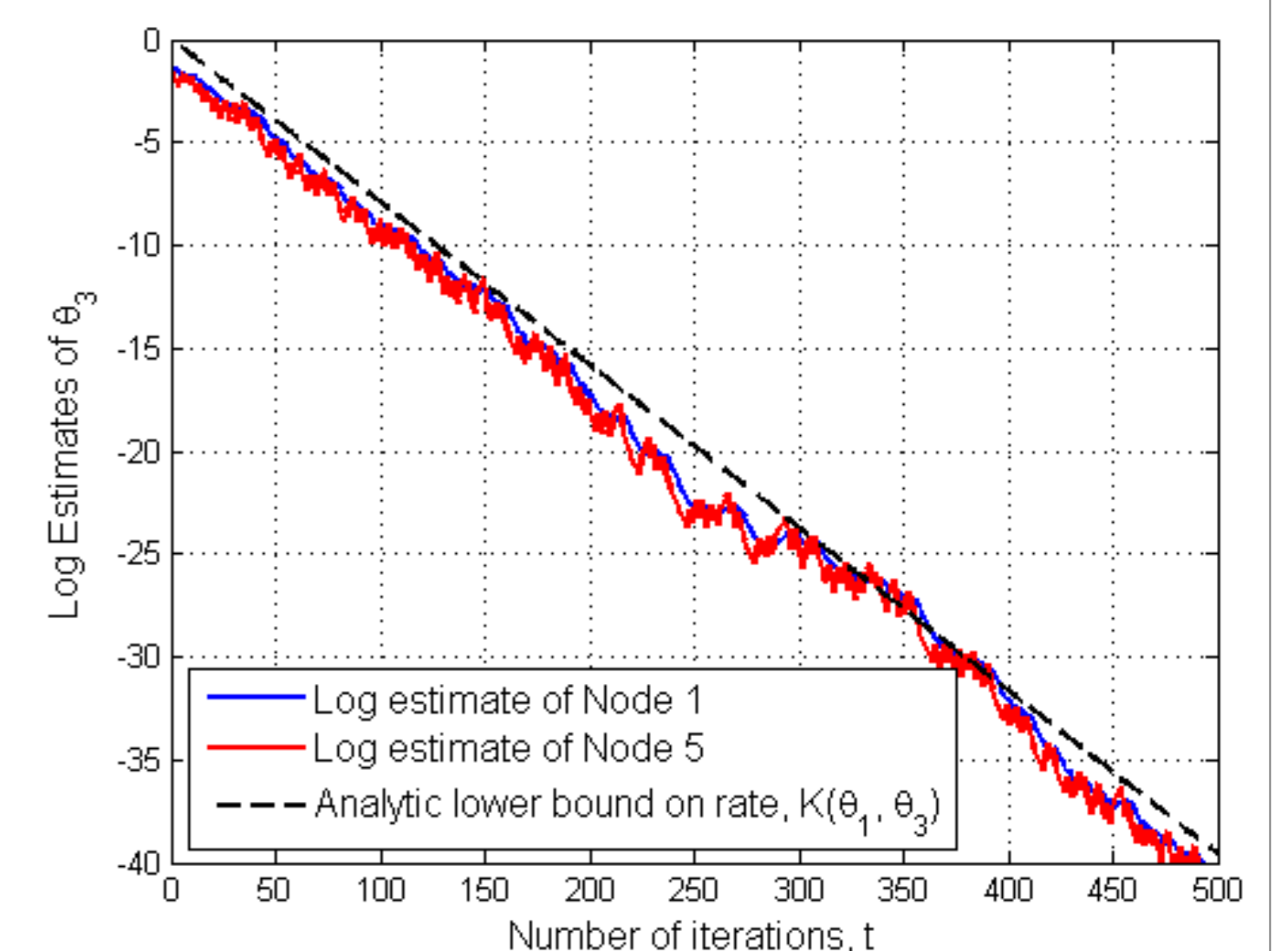
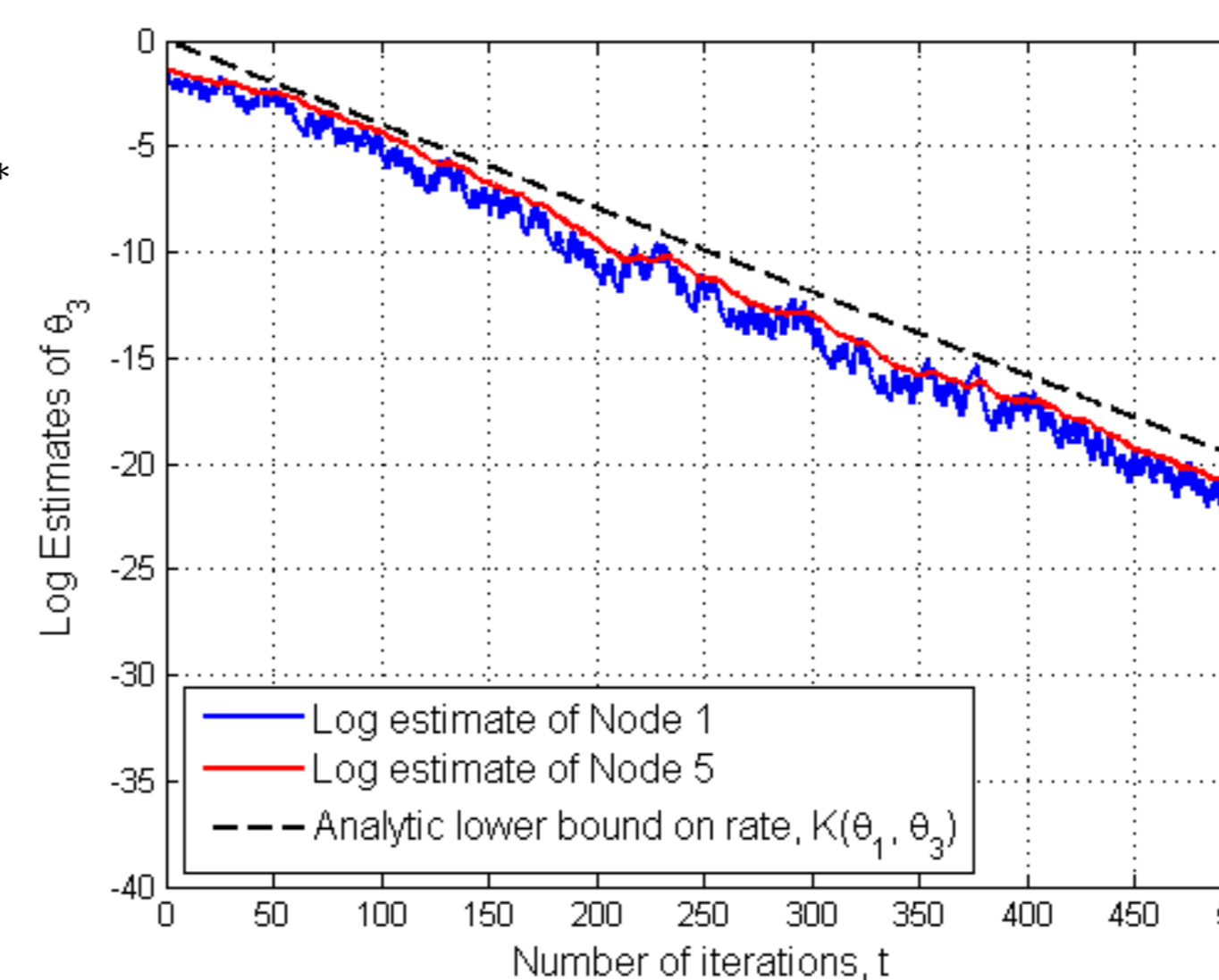
- Otherwise 0.
- Node  $i$  is uninformed if  $f_i(\cdot; \theta^*) = f_i(\cdot; \theta)$  for some  $\theta \neq \theta^*$
- Node  $i$  is informed if  $f_i(\cdot; \theta^*) \neq f_i(\cdot; \theta) \forall \theta \neq \theta^*$



Only node 1 is informed

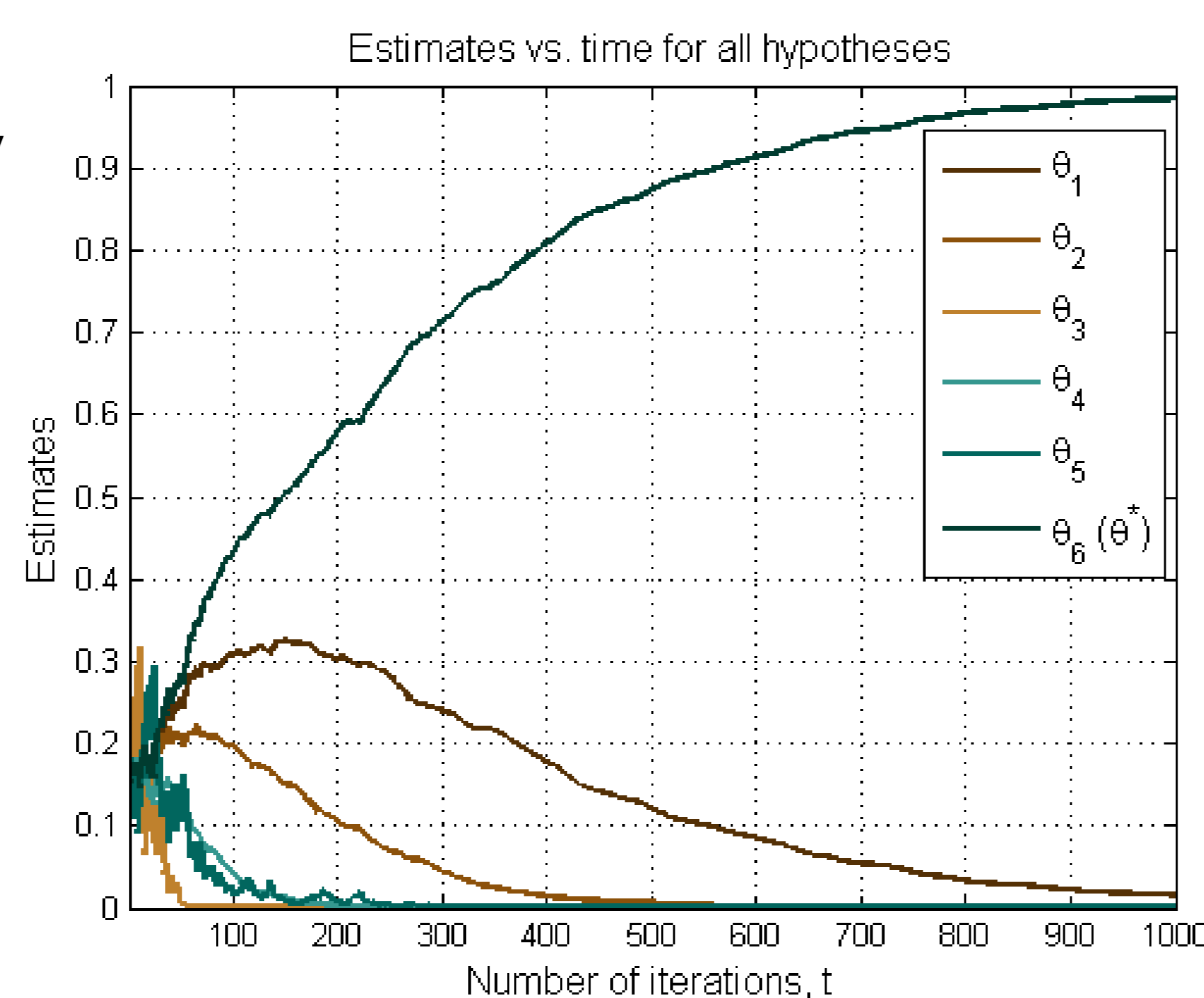


Only node 5 is informed

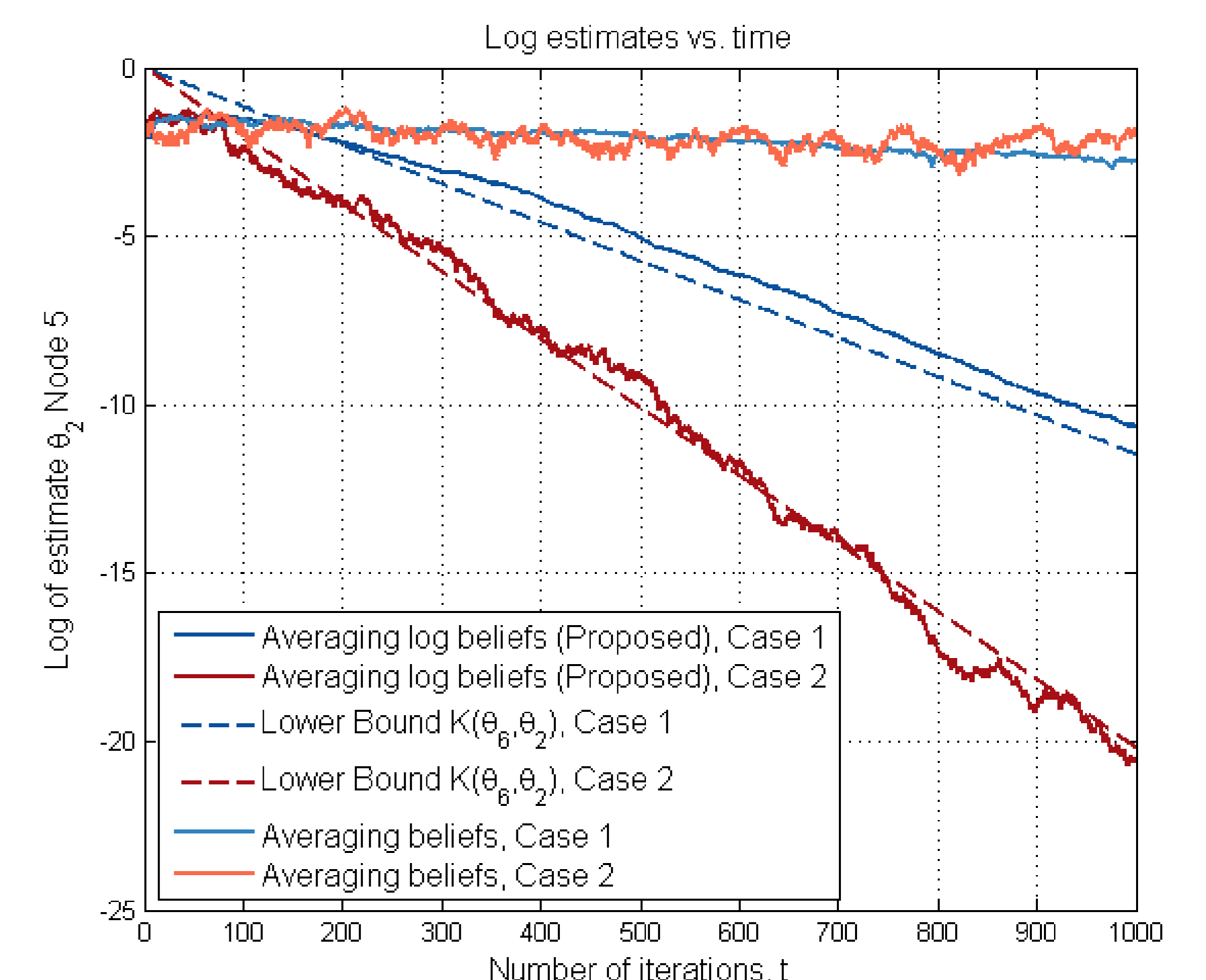


## Learning in a Co-authorship network

- Network is an undirected weighted network of co-authorships formed from high-energy theory collaborations over a period of 5 years.
- Weights capture strength of collaboration [3].
- Set of hypotheses is  $\Theta = \{\theta_1, \theta_2, \dots, \theta_6\}$  and  $\theta^* = \theta_6$
- Case 1:
  - Scientists are randomly divided into 5 groups.
  - Each group can distinguish between  $\theta_6$  and some  $\theta \neq \theta_6$
- None of them can individually learn  $\theta_6$  but using the proposed rule, nodes learn  $\theta_6$ , as shown in adjacent figure.



- We compare our rule with existing one in the literature where averaging of log-beliefs is replaced with averaging the beliefs [2].
- We compare the performance in two cases.
- Case 2:
  - Scientists are randomly divided into 10 groups.
  - Each group can distinguish between  $\theta_6$  and some  $\theta_1 \neq \theta_6$  and some  $\theta_j \neq \theta_6$
- Our rule performs faster than the previous rule in both the cases.
- We show this theoretically in [1].



### References:

1. A. Jadbababie, P.Molavi, and A. Tahbaz-Salehi, "Information Heterogeneity and the speed of learning in social networks", Columbia Business School Research Paper No.13-28, June 2013.
2. A. Lalitha, A. Sarwate and T. Javidi, "Social learning and distributed hypothesis testing", in Proceedings of International Symposium on Information Theory (ISIT), July 2014.
3. M. E. J Newman, "Scientific collaboration networks ii. Shortest paths, weighted networks and centrality", Phys. Rev. E, vol. 64, p. 016132, June 2001.